Write your name and student number in the top left corner of each page

1. Determine the z-transform of the following sequences and their respective ROCs including the zeros and poles (if applicable):

(a)
$$x[n] = \left(\frac{1}{3}\right)^n \mu[n]$$

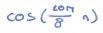
(b)
$$x[n] = \left(\frac{1}{3}\right)^n (\mu[n] - \mu[n-10])$$

Determine the inverse z-transform for the following functions:

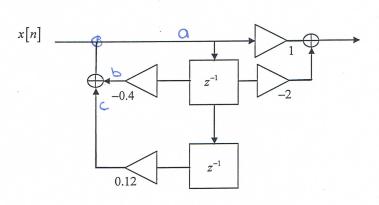
(c)
$$X(z) = \frac{1}{1 + 0.5z^{-1}}$$
, $|z| < 0.5$ anticau sa(
(d) $X(z) = \frac{1}{1 + 0.5z^{-1}}$, $|z| > 0.5$

(d)
$$X(z) = \frac{1}{1+0.5z^{-1}}, |z| > 0.5$$

2. A continuous-time sinusoidal system $x_a(t) = A\cos(\Omega_0 t + \varphi)$ can be uniquely recovered from its sampled version $x[n] = x_a(nT) = \cos(\Omega_0 nT)$. For what values of T is x[n] a periodic sequence? What is the fundamental period of x[n] if $\Omega_0 = 20$ radians and $T = \pi / 8$ seconds?



3. Consider the following LTI system:



Do=radians.

- (a) write down the transfer function of the system $H(z) = \frac{Y(z)}{X(z)}$
- (b) determine the ROC, poles and zeros and plot their positions in a zero-pole plot
- (c) what kind of a filter is this?

4. Suppose we have two four-point sequences x[n] and h[n] as follows:

$$x[n] = \cos(\pi n/2), \quad n = 0,1,2,3 \quad \text{and} \quad h[n] = 2^n, \quad n = 0,1,2,3$$

- (a) calculate the four point DFT X(k)(b) calculate the four point DFT H(k)
- (c) calculate the circular four point convolution $y[n] = x[n] \otimes h[n]$ directly
- (d) calculate y[n] by multiplying X(k) and H(k) and performing the inverse DFT
- 5. The z-transform of a causal sequence h[n] is given by:

$$H(z) = \frac{z(z+2.0)}{(z-0.2)(z+0.6)}$$

Determine the causal sequence h[n] by partial-fraction expansion of H(z)

6. Bonus Question

- (a) Discuss the advantages and disadvantages of IIR digital filter systems as compared To FIR digital filter systems
- (b) Describe how to use the wide knowledge of analog IIR filters for digital filter design